

# A well-balanced scheme for the Euler equations with gravity

**Vivien Desveaux**

July 10th 2014, Würzburg

Joint work with:

- Markus Zenk (Würzburg)
- Christian Klingenberg (Würzburg)
- Christophe Berthon (Nantes)

# Outline

- 1 Introduction
- 2 Relaxation model
- 3 Relaxation scheme and main properties
- 4 Numerical results

# The system of Euler equation with gravity

$$\begin{cases} \partial_t \rho + \partial_x \rho u = 0 \\ \partial_t \rho u + \partial_x (\rho u^2 + p) = -\rho \partial_x \Phi \\ \partial_t E + \partial_x (E + p)u = -\rho u \partial_x \Phi \end{cases}$$

- $\rho$  : density
- $u$  : velocity
- $E = \rho e + \rho u^2/2$  : total energy, with  $e$  the internal energy
- $\tau := 1/\rho$ : specific volume
- $p = p(\tau, e)$  : pressure given by a general law
- $\Phi(x)$  : given smooth gravitational potential

# The system of Euler equation with gravity

$$\begin{cases} \partial_t \rho + \partial_x \rho u = 0 \\ \partial_t \rho u + \partial_x (\rho u^2 + p) = -\rho \partial_x \Phi \\ \partial_t E + \partial_x (E + p)u = -\rho u \partial_x \Phi \end{cases}$$

- We define

- ▶ the vector of conservative variables  $w = (\rho, \rho u, E)^T$ ,
- ▶ the flux function  $f(w) = (\rho u, \rho u^2 + p, (E + p)u)^T$ ,
- ▶ the source term  $s(w) = (0, -\rho, -\rho u)^T$ ,

to rewrite the system into the compact form

$$\partial_t w + \partial_x f(w) = s(w) \partial_x \Phi.$$

- The set of physical admissible states is

$$\Omega = \left\{ w \in \mathbb{R}^3, \quad \rho > 0, \quad e > 0 \right\}.$$

# Steady states

The steady states at rest are described by

$$\begin{cases} u = 0 \\ \partial_x p = -\rho \partial_x \Phi \end{cases}$$

## Polytropic steady states

$$\begin{cases} u = 0 \\ p = K \rho^\gamma \end{cases} \Leftrightarrow \begin{cases} u = 0 \\ \rho = \left( \frac{\gamma-1}{K\gamma} (C - \Phi) \right)^{\frac{1}{\gamma-1}} \\ p = K^{-\frac{1}{\gamma-1}} \left( \frac{\gamma-1}{\gamma} (C - \Phi) \right)^{\frac{\gamma}{\gamma-1}} \end{cases}$$

$\gamma \rightarrow 1$ :

Isothermal equilibrium

$\gamma \rightarrow \infty$ :

Incompressible equilibrium

$$\begin{cases} u = 0 \\ \rho = e^{\frac{C-\Phi}{K}} \\ p = K e^{\frac{C-\Phi}{K}} \end{cases}$$

$$\begin{cases} u = 0 \\ \rho = \text{constant} \\ p + \rho \Phi = \text{constant} \end{cases}$$

# Entropy

The pressure is assumed to satisfy the second law of thermodynamics  
 $\Rightarrow$  existence of a specific entropy  $s(\tau, e)$  which satisfies

$$-Tds = de + pd\tau, \quad \text{with } T > 0 \text{ the temperature}$$

To rule out the unphysical solutions, the system is endowed with the following entropy inequalities:

$$\partial_t \rho \mathcal{F}(s) + \partial_x \rho \mathcal{F}(s) u \leq 0,$$

for all smooth function  $\mathcal{F}$  such that  $w \mapsto \rho \mathcal{F}(s)$  is strictly convex.

# Objectives

Derive a numerical scheme which has the following properties:

- Preservation of the set  $\Omega$
- Accurate approximation of all the steady states at rest
- Exact capture of the specific steady states (polytropic, isothermal, incompressible)
- Discrete entropy inequalities
- General gravitational potential and general pressure law

## Means

- Finite volume method (approximate Riemann solver)
- Relaxation method

# The relaxation method without source term

- Initial system:

$$\partial_t w + \partial_x f(w) = 0. \quad (1)$$

- Relaxation system:

$$\partial_t W + \partial_x F(W) = \frac{1}{\varepsilon} R(W), \quad (2)$$

- ▶ (2) should formally gives back (1) when  $\varepsilon \rightarrow 0$ .
  - ▶ (2) should be “simpler” than (1) (e.g. only linearly degenerate fields)

- The relaxation scheme is based on a splitting strategy:

**Time evolution:** We evolve the initial data by the Godunov scheme for the system  $\partial_t W + \partial_x F(W) = 0$  (i.e.  $\varepsilon = +\infty$ ).

$\Rightarrow$  We need the exact solution of the Riemann problem

**Relaxation:** We take into account the relaxation source term by solving  $\partial_t W = \frac{1}{\varepsilon} R(W)$  then taking the limit for  $\varepsilon \rightarrow 0$ .



# The Suliciu model ([Suliciu '98], [Bouchut '04]...)

$$\left\{ \begin{array}{l} \partial_t \rho + \partial_x \rho u = 0 \\ \partial_t \rho u + \partial_x (\rho u^2 + \pi) = -\rho \partial_x \Phi \\ \partial_t E + \partial_x (E + \pi) u = -\rho u \partial_x \Phi \\ \partial_t \rho \pi + \partial_x (\rho \pi + a^2) u = \frac{\rho}{\varepsilon} (p(\tau, e) - \pi) \\ \partial_t \Phi = 0 \end{array} \right. \quad \begin{array}{l} \text{Equilibrium} \\ \pi = p(\tau, e) \end{array}$$

**Eigenvalues:**  $u - \frac{a}{\rho}, \quad 0, \quad u, \quad u + \frac{a}{\rho}$

**Advantage:**

- All the fields are linearly degenerate

**Difficulties:**

- The order of the eigenvalues is not fixed *a priori*
- The Riemann invariants for the eigenvalue 0 are strongly nonlinear

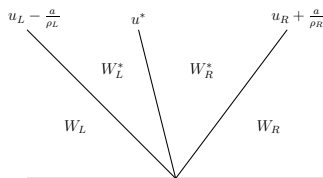
# Relaxation model with moving gravity

$$\left\{ \begin{array}{l} \partial_t \rho + \partial_x \rho u = 0 \\ \partial_t \rho u + \partial_x (\rho u^2 + \pi) = -\rho \partial_x Z \\ \partial_t E + \partial_x (E + \pi) u = -\rho u \partial_x Z \\ \partial_t \rho \pi + \partial_x (\rho \pi + a^2) u = \frac{\rho}{\varepsilon} (p(\tau, e) - \pi) \\ \partial_t \rho Z + \partial_x \rho Z u = \frac{\rho}{\varepsilon} (\Phi - Z) \end{array} \right. \quad \begin{array}{l} \text{Equilibrium} \\ \pi = p(\tau, e) \\ Z = \Phi \end{array}$$

- Eigenvalues:  $u - \frac{a}{\rho}$ ,  $u$ ,  $u + \frac{a}{\rho}$
- All the fields are linearly degenerate
- Fixed order of the eigenvalues:  $u - \frac{a}{\rho} < u < u + \frac{a}{\rho}$
- There is a **missing Riemann invariant** in order to determine a unique Riemann solution  
 $\Rightarrow$  We need a closure relation

# Relaxation model with moving gravity

$$\left\{ \begin{array}{l} \partial_t \rho + \partial_x \rho u = 0 \\ \partial_t \rho u + \partial_x (\rho u^2 + \pi) = -\rho \partial_x Z \\ \partial_t E + \partial_x (E + \pi) u = -\rho u \partial_x Z \\ \partial_t \rho \pi + \partial_x (\rho \pi + a^2) u = \frac{\rho}{\varepsilon} (p(\tau, e) - \pi) \\ \partial_t \rho Z + \partial_x \rho Z u = \frac{\rho}{\varepsilon} (\Phi - Z) \end{array} \right.$$



To approximate the equation

$$\partial_x p = -\rho \partial_x \Phi \quad \begin{array}{c} \Longleftrightarrow \\ \text{equilibrium} \\ \pi = p(\tau, e) \\ Z = \Phi \end{array} \quad \partial_x \pi = -\rho \partial_x Z,$$

we propose the following closure relation:

$$\frac{\pi_R^* - \pi_L^*}{\Delta x} = -\bar{\rho}(\rho_L, \rho_R) \frac{Z_R - Z_L}{\Delta x},$$

where  $\bar{\rho}$  is a suitable  $\rho$ -average (defined later)

# Approximate Riemann solver

Equilibrium state:

$$W^{eq}(w) = (\rho, \rho u, E, \rho p(\tau, e), \rho \Phi)^T$$

## Theorem

*With the closure equation, the Riemann problem admits a unique solution  $W_{\mathcal{R}}\left(\frac{x}{t}, W_L, W_R\right)$ .*

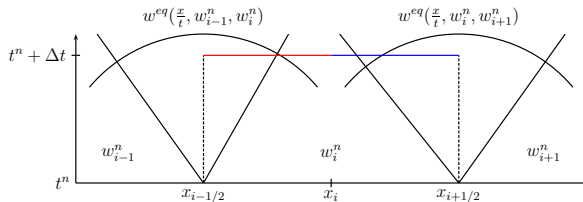
*Moreover,*

$$w^{eq}\left(\frac{x}{t}, w_L, w_R\right) := W_{\mathcal{R}}^{(\rho, \rho u, E)}\left(\frac{x}{t}, W^{eq}(w_L), W^{eq}(w_R)\right)$$

*defines an approximate Riemann solver (in the sense of Harten, Lax and van Leer) for the Euler equations with gravity.*

# The relaxation scheme

$w_i^n$ : approximation of the solution on the cell  $(x_{i-1/2}, x_{i+1/2})$  at time  $t^n$



CFL restriction

$$\frac{\Delta t}{\Delta x} \max_{i \in \mathbb{Z}} \left| u_i^n \pm \frac{a}{\rho_i^n} \right| \leq \frac{1}{2}$$

The update at time  $t^{n+1} = t^n + \Delta t$  is defined by

$$\begin{aligned} w_i^{n+1} = & \frac{1}{\Delta x} \int_{x_{i-1/2}}^{x_i} w^{eq} \left( \frac{x - x_{i-1/2}}{\Delta t}, w_{i-1}^n, w_i^n \right) dx \\ & + \frac{1}{\Delta x} \int_{x_i}^{x_{i+1/2}} w^{eq} \left( \frac{x - x_{i+1/2}}{\Delta t}, w_i^n, w_{i+1}^n \right) dx \end{aligned}$$

## Theorem (Robustness)

Assume the parameter  $a$  satisfies the following inequalities:

$$u_L - \frac{a}{\rho_L} < u^* < u_R + \frac{a}{\rho_R},$$

$$e_L + \frac{\pi_L^{*2} - p_L^2}{2a^2} > 0, \quad e_R + \frac{\pi_R^{*2} - p_R^2}{2a^2} > 0$$

Then the relaxation scheme preserves the set of physical states  $\Omega$ .

## Theorem (Well-balancedness)

The relaxation scheme preserves exactly the initial data satisfying

$$\begin{cases} u_i^0 = 0, \\ \frac{p_{i+1}^0 - p_i^0}{\Delta x} = -\bar{\rho}(\rho_i^0, \rho_{i+1}^0) \frac{\Phi_{i+1} - \Phi_i}{\Delta x}. \end{cases}$$

Then  $w_i^{n+1} = w_i^n$ ,  $\forall i \in \mathbb{Z}$ ,  $\forall n \in \mathbb{N}$ .

## Theorem (Exact preservation of the specific steady states)

For  $\rho_R \neq \rho_L$ , we define  $\bar{\gamma} = \frac{\ln p_R - \ln p_L}{\ln \rho_R - \ln \rho_L}$ .

Assume the average function  $\bar{\rho}$  is defined by

$$\bar{\rho}(\rho_L, \rho_R) = \begin{cases} \frac{\bar{\gamma}-1}{\bar{\gamma}} \frac{\rho_R^{\bar{\gamma}} - \rho_L^{\bar{\gamma}}}{\rho_R^{\bar{\gamma}-1} - \rho_L^{\bar{\gamma}-1}} & \text{if } \rho_L \neq \rho_R \text{ and } \bar{\gamma} \neq 1, \\ \frac{\rho_R - \rho_L}{\ln \rho_R - \ln \rho_L} & \text{if } \rho_L \neq \rho_R \text{ and } \bar{\gamma} = 1, \\ \rho_L & \text{if } \rho_L = \rho_R. \end{cases}$$

Then the relaxation scheme preserves exactly the polytropic, the isothermal and the incompressible equilibria:

if the initial solution is given by

$$\begin{cases} u_i^0 = 0, \\ \rho_i^0 = \left( \frac{\gamma-1}{K\gamma} (C - \Phi_i) \right)^{\frac{1}{\gamma-1}}, \\ p_i^0 = K^{-\frac{1}{\gamma-1}} \left( \frac{\gamma-1}{\gamma} (C - \Phi_i) \right)^{\frac{\gamma}{\gamma-1}}, \end{cases} \quad \text{or} \quad \begin{cases} u_i^0 = 0, \\ \rho_i^0 = e^{\frac{C - \Phi_i}{K}}, \\ p_i^0 = K e^{\frac{C - \Phi_i}{K}}, \end{cases} \quad \text{or} \quad \begin{cases} u_i^0 = 0, \\ \rho_i^0 = \text{constant}, \\ p_i^0 + \rho_i^0 \Phi_i = \text{constant}, \end{cases}$$

then the approximate solution stays at rest:  $w_i^n = w_i^0, \quad \forall n \in \mathbb{N}$ .

## Theorem

Assume the parameter  $a$  satisfy the following Whitham conditions:

$$a^2 > p(\tau_{L,R}, e_{L,R}) \partial_e p(\tau_{L,R}, e_{L,R}) - \partial_\tau p(\tau_{L,R}, e_{L,R}),$$

$$a^2 > p(\tau_{L,R}^*, e_{L,R}^*) \partial_e p(\tau_{L,R}^*, e_{L,R}^*) - \partial_\tau p(\tau_{L,R}^*, e_{L,R}^*).$$

Then the relaxation scheme satisfies

$$\rho_i^{n+1} \mathcal{F}(s_i^{n+1}) \leq \rho_i^n \mathcal{F}(s_i^n) - \frac{\Delta t}{\Delta x} \left( \{\rho \mathcal{F}(s) u\}_{i+1/2}^n - \{\rho \mathcal{F}(s) u\}_{i-1/2}^n \right)$$

for all smooth function  $\mathcal{F}$  such that  $w \mapsto \rho \mathcal{F}(s)$  is strictly convex.

The entropy numerical flux is defined by

$$\{\rho \mathcal{F}(s) u\}_{i+1/2}^n = F_{i+1/2}^\rho \times \begin{cases} \mathcal{F}(s_i^n) & \text{if } F_{i+1/2}^\rho > 0, \\ \mathcal{F}(s_{i+1}^n) & \text{if } F_{i+1/2}^\rho < 0, \end{cases}$$

with  $F_{i+1/2}^\rho$  the  $\rho$ -component of the numerical flux.



# Isothermal atmosphere

- Computational domain:  $[0, 1]$  until time  $T = 0.25$

- $\Phi(x) = x^2$

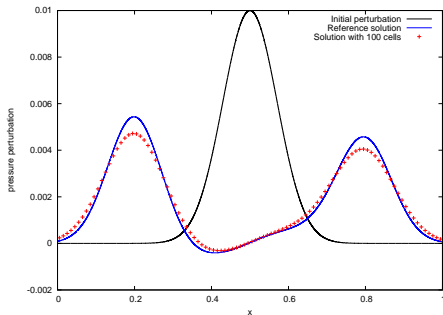
- Initial condition: 
$$\begin{cases} \rho_0(x) = e^{-x^2} \\ u_0(x) = 0 \\ p_0(x) = e^{-x^2} \end{cases}$$

- $L^1$  error:

$N$	Density	Velocity
100	1.15E-16	7.62E-17
200	1.77E-16	1.34E-16
400	3.01E-16	1.14E-16
800	4.37E-16	1.33E-16
1600	7.32E-16	1.91E-16
3200	1.18E-15	2.52E-16

# Small perturbation of an isothermal atmosphere

- Computational domain:  $[0, 1]$  until time  $T = 0.25$
- $\Phi(x) = x$
- Initial condition: 
$$\begin{cases} \rho_0(x) = e^{-x} \\ u_0(x) = 0 \\ p_0(x) = e^{-x} + 0.01e^{100(x-0.5)^2} \end{cases}$$
- Pressure perturbation:  $\delta p = p - p_0$



# Non-hydrostatic steady state

- Computational domain:  $[0, 1]$  with periodic boundary conditions until time  $T = 1$
- $\Phi(x) = \sin(2\pi x)$
- Initial condition: 
$$\begin{cases} \rho_0(x) = 3 + 2 \sin(2\pi x) \\ u_0(x) = 0 \\ p_0(x) = 3 + 3 \sin(2\pi x) - \frac{1}{2} \cos(4\pi x) \end{cases}$$

We check easily  $\partial_x p_0 + \rho_0 \partial_x \Phi = 0$

- $L^1$  error:

$N$	Density		Velocity	
100	4.46E-05	—	2.03E-05	—
200	7.11E-06	2.65	5.29E-06	1.94
400	1.23E-06	2.53	1.34E-06	1.98
800	2.35E-07	2.39	3.37E-07	1.99
1600	5.02E-08	2.23	8.44E-08	2.00
3200	1.15E-08	2.13	2.11E-08	2.00

# Perspectives

- Extension to second-order
  - ▶ MUSCL technique written as a convex combination of first-order scheme
  - ▶ Difficulty to preserve the well-balanced property
  - ▶ Possible solution: use a unusual set of variables for the reconstruction
- Extension to unstructured 2D
  - ▶ Convex combination of 1D scheme by interface