A well-balanced relaxation scheme for the Euler equations with gravity

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NumHyp 2013 conference, Aachen, September 26, 2013



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The system of Euler equations with gravity

$$\begin{cases} \partial_t \rho + \partial_x \rho u = 0\\ \partial_t \rho u + \partial_x \left(\rho u^2 + p\right) = -\rho \partial_x \phi\\ \partial_t E + \partial_x (u(E+p)) = -\rho u \partial_x \phi \end{cases}$$

- $\rho$ : density
  - u: velocity

 $E = \rho e + \rho u^2/2$ : total energy, with *e* the internal energy  $p = p(\rho, e)$ : pressure given by a general law  $\phi(x)$ : gravitational potential (example:  $\phi(x) = gx$ )

• Hyperbolicity assumption:

$$c^2 := \partial_\rho p + \frac{p}{\rho^2} \partial_e p > 0$$

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- We define
  - the vector of conservative variables w = (ρ, ρu, E)<sup>T</sup>,
    the flux function f(w) = (ρu, ρu<sup>2</sup> + p, u(E + p))<sup>T</sup>,

  - the source term  $s(w) = (0, -\rho, -\rho u)^T$ ,

to rewrite the system into the compact form

$$\partial_t w + \partial_x f(w) = s(w) \partial_x \phi.$$

• The set of physical admissible states is

$$\Omega = \left\{ w \in \mathbb{R}^3, \quad \rho > 0, \quad E - \rho u^2/2 > 0 \right\}.$$

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#### Steady states

At the continuous level, the steady states at rest are governed by the ODE

$$\begin{cases} u \equiv 0, \\ \partial_x p = -\rho \partial_x \phi. \end{cases}$$

We cannot obtain an explicit expression of all the steady states.  $\rightarrow$  We have to define the steady states at the discrete level.

2 / 12

# Discrete steady states and well-balanced scheme

- Space discretization: cells  $[x_{i-1/2}, x_{i+1/2})$  with constant size  $\Delta x = x_{i+1/2} x_{i-1/2}$
- $w_i^n$ : approximation of the solution of the system at time  $t^n$  on the cell  $[x_{i-1/2}, x_{i+1/2})$
- Discretization of the potential  $\phi$ :  $\phi_i = \frac{1}{\Delta x} \int_{x_{i-1/2}}^{x_{i+1/2}} \phi(x) dx$

## Definition (Discrete steady states)

An approximation  $(w_i^n)_{i \in \mathbb{Z}}$  is a discrete steady state, if for all  $i \in \mathbb{Z}$ , we have  $u_i^n = 0$ , and  $p_{i+1}^n - p_i^n = -\frac{\rho_i^n + \rho_{i+1}^n}{2}(\phi_{i+1} - \phi_i).$ 

## Definition (Well-balanced scheme)

A numerical scheme is well-balanced if for all discrete steady state  $(w_i^n)_{i \in \mathbb{Z}}$ , the scheme satisfies  $w_i^{n+1} = w_i^n$ , for all  $i \in \mathbb{Z}$ .

# The relaxation method without source term

• Aim: derive a numerical scheme to approximate the solutions of

$$\partial_t w + \partial_x f(w) = 0.$$

• We introduce a relaxation system

$$\partial_t W + \partial_x F(W) = \frac{1}{\varepsilon} R(W),$$

which should formally give back the original system when  $\varepsilon \to 0$ . Moreover the relaxation system should be "simpler" than the original system (e.g. only linearly degenerate fields)

 The relaxation scheme is based on a splitting strategy: Time evolution: We evolve the initial data by the Godunov scheme for the system ∂<sub>t</sub> W + ∂<sub>x</sub>F(W) = 0 (i.e. ε = +∞). Relaxation: We take into account the relaxation source term by solving ∂<sub>t</sub> W = <sup>1</sup>/<sub>ε</sub>R(W) then taking the limit for ε → 0.

4 / 12

The Suliciu model for the Euler equations with gravity

$$\begin{cases} \partial_t \rho + \partial_x \rho u = 0\\ \partial_t \rho u + \partial_x (\rho u^2 + \pi) = -\rho \partial_x \phi\\ \partial_t E + \partial_x (u(E + \pi)) = -\rho u \partial_x \phi\\ \partial_t \rho \pi + \partial_x (u(\rho \pi + \nu^2)) = \frac{\rho}{\varepsilon} (p(\rho, e) - \pi) \end{cases}$$

The relaxation parameter  $\nu > 0$  must satisfy the Whitham condition:

$\nu^2$	~	_2	2	
ν	/	$\rho$	C	•

Eigenvalues	Riemann invariants	
$u \pm \frac{\nu}{\rho}$	$u\pmrac{ u}{ ho}, \pi\mp u u,  u^2e-rac{\pi^2}{2}, \phi$	
$u (\times 2)$	$u,  \pi,  \phi$	
0	$\rho u,  \pi + \frac{\nu^2}{\rho},  \nu^2 e - \frac{\pi^2}{2},  \phi + \frac{u^2}{2} - \frac{\nu^2}{2\rho^2}$	

Difficulties to compute the solution of the Riemann problem:

- the order of the eigenvalues is not determined a priori
- there are strong nonlinearities in the Riemann invariants for the eigenvalue 0

Relaxation model with moving gravity

$$\begin{cases} \partial_t \rho + \partial_x \rho u = 0\\ \partial_t \rho u + \partial_x (\rho u^2 + \pi) = -\rho \partial_x a\\ \partial_t E + \partial_x (u(E + \pi)) = -\rho u \partial_x a\\ \partial_t \rho \pi + \partial_x (u(\rho \pi + \nu^2)) = \frac{\rho}{\varepsilon} (p(\rho, e) - \pi)\\ \partial_t a + u \partial_x a = \frac{1}{\varepsilon} (\phi - a) \end{cases}$$

Eigenvalues	Riemann invariants			
$u \pm \frac{\nu}{\rho}$	$u \pm \frac{\nu}{\rho}$ ,	$\pi \mp \nu u,$	$\nu^2 e - \frac{\pi^2}{2},$	a
$u (\times 3)$		u		

- The order of the eigenvalues is fixed:  $u \frac{\nu}{\rho} < u < u + \frac{\nu}{\rho}$
- There is a missing invariant for the eigenvalue u
   ⇒ we need a closure equation

# The Riemann problem



• 7 unknowns:

 $u^*, \ \rho^*_{L,R}, \ e^*_{L,R}, \ \pi^*_{L,R}$ 

• 6 equations given by the Riemann invariants  $\tau^2$ 

$$u \pm \frac{\nu}{\rho}, \ \pi \mp \nu u, \ \nu^2 e - \frac{\pi^2}{2}$$

• Closure equation:  $\pi_R^* - \pi_L^* = -\frac{\rho_L + \rho_R}{2}(a_R - a_L)$ 

#### Solution of the Riemann problem

$$u^{*} = \frac{u_{L} + u_{R}}{2} - \frac{\pi_{R} - \pi_{L}}{2\nu} - \frac{\rho_{L} + \rho_{R}}{2} \frac{a_{R} - a_{L}}{2\nu}$$

$$\pi_{L}^{*} = \pi_{L} + \nu(u_{L} - u^{*}) \qquad \pi_{R}^{*} = \pi_{R} + \nu(u^{*} - u_{R})$$

$$\frac{1}{\rho_{L}^{*}} = \frac{1}{\rho_{L}} + \frac{u^{*} - u_{L}}{\nu} \qquad \frac{1}{\rho_{R}^{*}} = \frac{1}{\rho_{R}} + \frac{u_{R} - u^{*}}{\nu}$$

$$e_{L}^{*} = e_{L} + \frac{\pi_{L}^{*2} - \pi_{L}^{2}}{2\nu^{2}} \qquad e_{R}^{*} = e_{R} + \frac{\pi_{R}^{*2} - \pi_{R}^{2}}{2\nu^{2}}$$

Reformulation into a fully determined model

$$\begin{aligned} \partial_t \rho + \partial_x \rho u &= 0\\ \partial_t \rho u + \partial_x (\rho u^2 + \pi) &= -\frac{X^- + X^+}{2} \partial_x a\\ \partial_t E + \partial_x (u(E + \pi)) &= -\frac{X^- + X^+}{2} u \partial_x a\\ \partial_t \rho \pi + \partial_x (u(\rho \pi + \nu^2)) &= \frac{\rho}{\varepsilon} (p(\rho, e) - \pi)\\ \partial_t a + u \partial_x a &= \frac{1}{\varepsilon} (\phi - a)\\ \partial_t X^- + (u - \delta) \partial_x X^- &= \frac{1}{\varepsilon} (\rho - X^-)\\ \partial_t X^+ + (u + \delta) \partial_x X^+ &= \frac{1}{\varepsilon} (\rho - X^+) \end{aligned}$$

Eigenvalues	Riemann invariants		
$u \pm \frac{\nu}{\rho}$	$u \pm \frac{\nu}{\rho},  \pi \mp \nu u,  \nu^2 e - \frac{\pi^2}{2},  a,  X^-,  X^+$		
u~( imes 3)	$u,  \pi + \frac{X^- + X^+}{2}a,  X^-,  X^+$		
$u-\delta$	$ ho,  u,  e,  \pi,  a,  X^+$		
$u + \delta$	$ ho,  u,  e,  \pi,  a,  X^-$		

- For  $\delta$  small enough, the order of the eigenvalues is fixed:  $u - \frac{\nu}{\rho} < u - \delta < u < u + \delta < u + \frac{\nu}{\rho}$
- There is a full set of Riemann invariants

V. Desveaux

# The Riemann problem for the reformulated model



- 7 unknowns:
  - $u^*, \ \rho^*_{L,R}, \ e^*_{L,R}, \ \pi^*_{L,R}$
- The equations coming from the Riemann invariants  $u \pm \frac{\nu}{\rho}$ ,  $\pi \mp \nu u$  and  $\nu^2 e \frac{\pi^2}{2}$  are the same as in the previous model.
- The last equation is  $\pi_R^* \pi_L^* = -\frac{X_R^- + X_L^+}{2}(a_R a_L)$ . For an initial data at the relaxation equilibrium (i.e.  $\pi = p(\rho, e), a = \phi, X^{\pm} = \rho$ ), we recover the closure equation of the previous model.

The two models have the "same" solution of the Riemann problem for an initial data at the relaxation equilibrium.

 $\Rightarrow$  both models lead to the same numerical scheme.

## The relaxation scheme

The relaxation scheme associated with both previous models writes

$$\begin{split} w_i^{n+1} &= w_i^n - \frac{\Delta t}{\Delta x} \left( F(w_i^n, w_{i+1}^n) - F(w_{i-1}^n, w_i^n) \right) \\ &+ \frac{\Delta t}{2} \left( s^+(w_{i-1}^n, w_i^n) \frac{\phi_i - \phi_{i-1}}{\Delta x} + s^-(w_i^n, w_{i+1}^n) \frac{\phi_{i+1} - \phi_i}{\Delta x} \right), \end{split}$$

where the numerical flux is defined by

$$f(w_L, w_R) = \begin{cases} \left(\rho_L u_L, & \rho_L u_L^2 + p_L, & u_L(E_L + p_L)\right)^T & \text{if } u_L - \frac{\nu}{\rho_L} > 0, \\ \left(\rho_L^* u^*, & \rho_L^* (u^*)^2 + \pi_L^*, & u^* (E_L^* + \pi_L^*)\right)^T & \text{if } u_L - \frac{\nu}{\rho_L} < 0 < u^*, \\ \left(\rho_R^* u^*, & \rho_R^* (u^*)^2 + \pi_R^*, & u^* (E_R^* + \pi_R^*)\right)^T & \text{if } u^* < 0 < u_R + \frac{\nu}{\rho_R}, \\ \left(\rho_R u_R, & \rho_R u_R^2 + p_R, & u_R(E_R + p_R)\right)^T & \text{if } u_R + \frac{\nu}{\rho_R} < 0, \end{cases}$$

and the numerical source terms are defined by

$$s^{+}(w_{L}, w_{R}) = -(\operatorname{sgn}(u^{*}) + 1) \left(0, \frac{\rho_{L} + \rho_{R}}{2}, \frac{\rho_{L} + \rho_{R}}{2} u^{*}\right)^{T},$$

$$s^{-}(w_{L}, w_{R}) = (\operatorname{sgn}(u^{*}) - 1) \left(0, \frac{\rho_{L} + \rho_{R}}{2}, \frac{\rho_{L} + \rho_{R}}{2} u^{*}\right)^{T}.$$

# Properties of the relaxation scheme

## Theorem (Well-balancedness)

The relaxation scheme preserves the steady states at rest:

$$\forall i \in \mathbb{Z}, \begin{cases} u_i^n = 0\\ p_{i+1}^n - p_i^n = -\frac{\rho_i^n + \rho_{i+1}^n}{2}(\phi_{i+1} - \phi_i) \end{cases} \Rightarrow \forall i \in \mathbb{Z}, \ w_i^{n+1} = w_i^n \end{cases}$$

## Theorem (Robustness)

Assume the parameter  $\nu$  satisfies the following inequalities:

$$u_L - \frac{\nu}{\rho_L} < u^* < u_R + \frac{\nu}{\rho_R}, \quad e_L + \frac{\pi_L^{*2} - p_L^2}{2\nu^2} > 0, \quad e_R + \frac{\pi_R^{*2} - p_R^2}{2\nu^2} > 0.$$

Assume the following CFL condition is satisfied:

$$\frac{\Delta t}{\Delta x} \max_{i \in \mathbb{Z}} |u_i^n \pm \nu / \rho_i^n| \le \frac{1}{2}$$

Then the relaxation scheme preserves the set of physical states:

 $\forall i \in \mathbb{Z}, \ \rho_i^n > 0 \ and \ e_i^n > 0 \quad \Rightarrow \quad \forall i \in \mathbb{Z}, \ \rho_i^{n+1} > 0 \ and \ e_i^n > 0.$ 

Numerical test: perturbation of an hydrostatic atmosphere

- Perfect gas law:  $p = (\gamma - 1) \left(E - \rho u^2/2\right)$
- Constant gravitational field:  $\phi(x) = gx$
- Steady state  $w_s(x)$ : hydrostatic atmosphere

$$\begin{cases} \rho_s(x) = \left(1 - \frac{\gamma - 1}{\gamma} gx\right)^{\frac{1}{\gamma - 1}} \\ u_s(x) = 0 \\ p_s(x) = \rho_s(x)^{\gamma} \end{cases}$$

- Boundary condition:  $u(0, t) = 0.1 \sin(6\pi t)$
- Perturbation:  $\delta w(x, t) = w(x, t) - w_s(x)$



Final time perturbation in velocity  $\delta u(x, T)$  computed with 1.024 cells.

The reference solution is computed with 32.768 cells with the first-order relaxation scheme.

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12 / 12