Conditioning and Preconditioning in the Cone of SPD matrices

J-P. CHEHAB¹

¹LAMFA, UMR 7352, Université de Picardie Jules Verne, Amiens, France (jean-paul.chehab@u-picardie.fr)

May 18th, 2016

Joint work with Marcos Raydan (USB, Caracas)

(□) (@) (E) (E) =

Outline

Motivation Geometrical properties and Frobenius condition Number The cosine and the approximation to the inverse Iterative methods Numerical Results Concluding remarks

Motivation

2 Geometrical Properties

- The cosine and the approximation to the inverse
 - Choice of the merit function
 - Properties

Iterative methods

- Gradient Method
- Convergence results
- Simplified search Direction
- Sparse approximation

5 Numerical Results

6 Concluding remarks

Obervations

- The set $PD_n \subset S_n$ of the $n \times n$ SPD matrices possesses a cone structure
- The Identity matrix *Id* plays a centrale role : *Id* is a central ray (Taragaza (90'))
- Angle between matrices reveals as a central tool

-

Obervations

- The set $PD_n \subset S_n$ of the $n \times n$ SPD matrices possesses a cone structure
- The Identity matrix *Id* plays a centrale role : *Id* is a central ray (Taragaza (90'))
- Angle between matrices reveals as a central tool

Questions

- How to characterize the conditioning of the matrices in PD_n
- How to build (inverse) preconditioners in PD_n

3 b 4 3 b

It is natural to use the cosine to measure the angle between two matrices

$$\cos(A,B) = \frac{\langle A,B \rangle_F}{\|A\|_F \|B\|_F}$$

where $\langle A, B \rangle_F = Tr(B^T A)$ and $\|.\|_F$ is the Frobenius norm. We have the simple identities

< 回 > < 三 > < 三 >

It is natural to use the cosine to measure the angle between two matrices

$$\cos(A,B) = \frac{\langle A,B \rangle_F}{\|A\|_F \|B\|_F}$$

where $\langle A, B \rangle_F = Tr(B^T A)$ and $\|.\|_F$ is the Frobenius norm. We have the simple identities

•
$$\cos(A, Id) = \frac{Tr(A)}{\sqrt{n} ||A||_F}$$

• $\cos(A, Id) \cos(A^{-1}, Id) = \frac{Tr(A) Tr(A^{-1})}{n ||A||_F ||A^{-1}||_F}$
• $\cos(A, A^{-1}) = \frac{n}{||A||_F ||A^{-1}||_F}$

- 4 同 ト 4 三 ト 4 三 ト

It is natural to use the cosine to measure the angle between two matrices

$$\cos(A,B) = \frac{\langle A,B \rangle_F}{\|A\|_F \|B\|_F}$$

where $\langle A, B \rangle_F = Tr(B^T A)$ and $\|.\|_F$ is the Frobenius norm. We have the simple identities

• $\cos(A, Id) = \frac{Tr(A)}{\sqrt{n} ||A||_F}$ • $\cos(A, Id) \cos(A^{-1}, Id) = \frac{Tr(A) Tr(A^{-1})}{n ||A||_F ||A^{-1}||_F}$ • $\cos(A, A^{-1}) = \frac{n}{||A||_F ||A^{-1}||_F}$

The Frobenius condition number of A, $\kappa(A)_F = ||A||_F ||A^{-1}||_F$ is then related to the cosine of the angle that A and A^{-1} make with the central ray matrix Id, and also to the angle between A and A^{-1} .

It is natural to use the cosine to measure the angle between two matrices

$$\cos(A,B) = \frac{\langle A,B \rangle_F}{\|A\|_F \|B\|_F}$$

where $\langle A, B \rangle_F = Tr(B^T A)$ and $\|.\|_F$ is the Frobenius norm. We have the simple identities

• $\cos(A, Id) = \frac{Tr(A)}{\sqrt{n} ||A||_F}$ • $\cos(A, Id) \cos(A^{-1}, Id) = \frac{Tr(A) Tr(A^{-1})}{n ||A||_F ||A^{-1}||_F}$ • $\cos(A, A^{-1}) = \frac{n}{||A||_F ||A^{-1}||_F}$

The Frobenius condition number of A, $\kappa(A)_F = ||A||_F ||A^{-1}||_F$ is then related to the cosine of the angle that A and A^{-1} make with the central ray matrix Id, and also to the angle between A and A^{-1} .

Of course we would like to avoid to handle quantities with A^{-1} and then produce estimates of the condition number using A only

Properties

۲

۲

Identities and Properties

• $\kappa_F(A)$ expressed with distance between A and A^{-1}

$$\kappa(A)_F = n + \frac{1}{2} \left(\|A - A^{-1}\|_F^2 - (\|A\|_F - \|A^{-1}\|_F)^2 \right) \\ = n + \frac{1}{2} D(A, A^{-1}).$$

$$egin{aligned} &1+rac{1}{2n}D(A,A^{-1})\leq\kappa_2(A)\leq n+rac{1}{2}D(A,A^{-1})\ &\ &rac{1}{\kappa_2(A)}\leq\cos(A,A^{-1})\leq\cos(A,Id)\cos(A^{-1},Id) \end{aligned}$$

Properties (segue)

Properties

۲

۲

$$\frac{1}{n} \leq \frac{\cos(A, \mathit{Id})}{\cos(A^{-1}, \mathit{Id})} \leq n$$

$$\kappa_F(A) \geq \max(n, rac{\sqrt{n}}{\cos^2(A, \mathit{Id})})$$

• (Wolfowicz & Styan, 80') with
$$m = tr(A)/n, p = \sqrt{n-1}, s^2 = ||A||_F^2/n - m^2$$
,

$$\kappa_{\mathcal{F}}(\mathcal{A}) \geq \operatorname{Max}\left(n, \frac{\sqrt{n}}{\cos^2(\mathcal{A}, \mathit{Id})}, \left(1 + \frac{2s}{m - \frac{s}{p}}\right)\right)$$

イロン イロン イヨン イヨン

2

Properties (segue)

Properties

۲

۲

$$\frac{1}{n} \leq \frac{\cos(A, Id)}{\cos(A^{-1}, Id)} \leq n$$

$$\kappa_F(A) \geq \max(n, rac{\sqrt{n}}{\cos^2(A, \mathit{Id})})$$

• (Wolfowicz & Styan, 80') with
$$m = tr(A)/n, p = \sqrt{n-1}, s^2 = ||A||_F^2/n - m^2$$
,

$$\kappa_{\mathcal{F}}(\mathcal{A}) \geq \operatorname{Max}\left(n, \frac{\sqrt{n}}{\cos^2(\mathcal{A}, \mathit{Id})}, \left(1 + \frac{2s}{m - \frac{s}{\rho}}\right)\right)$$

Rmk : Statistical interpretation with M = m Id, spectral mean value matrix of A and $s^2 = ||A - M||_F^2/n$ is the variance, $\frac{s}{p}$ is the unbiased standard deviation.

イロト イヨト イヨト

Illustration



Choice of the merit function Properties

Approximation of the inverse using the Cosine

Let X_k be a sequence of matrices, then

$$\|Id - X_kA\|_F^2 = (\|Id\|_F - \|X_kA\|_F)^2 + 2(1 - \cos(Id, X_kA))\|Id\|_F \|X_kA\|_F$$

Then is X_k , is a sequence of matrices converging to A^{-1} assuming that $||X_kA||_F = \sqrt{n} = ||Id||_F$, we have

$$||Id - X_k A||_F^2 = 2n(1 - \cos(Id, X_k A))$$

IDEA : build X_k as minimizing sequence of $F(X) = 1 - \cos(Id, XA)$ **Rmk** : we could consider also $F_1(X) = 1 - \cos(Id, AX)$.

4 3 5 4 3 5 5

Choice of the merit function Properties

As seen above, these sets will play an important role

$$S = \{X \in \mathcal{M}_n(\mathbb{R}) / \|XA\|_F = \sqrt{n}\}, T = \{X \in \mathcal{M}_n(\mathbb{R}) / tr(XA) \ge 0\}$$

-1

•
$$F(X) = 0 \Longrightarrow X = \xi A^{-1}, \xi > 0$$

•
$$F(X) = 0$$
 and $X \in S \Longrightarrow X = A^{-1}$

< ロ > < 回 > < 回 > < 回 > < 回 >

Choice of the merit function Properties

As seen above, these sets will play an important role

$$S = \{X \in \mathcal{M}_n(\mathbb{R}) / \|XA\|_F = \sqrt{n}\}, T = \{X \in \mathcal{M}_n(\mathbb{R}) / tr(XA) \ge 0\}$$

1

Important remark : F(X) is invariant by positive scaling, say

$$F(\alpha X) = F(X)$$

This will give the boundness of approximating sequences of matrices when working in ${\cal S}$

⊒⇒ ∢ ⊒⇒

Choice of the merit function Properties

Basic properties of F and S

•
$$\nabla F(X) = \frac{1}{\|Id\|_F \|XA\|_F} \left(\frac{\langle XA, Id \rangle}{\|XA\|_F^2} XA - Id\right) A^T$$

•
$$< \nabla F(X), X >= 0, \forall X \in S$$

•
$$\frac{\sqrt{n}}{\|A\|_F} \leq \|X\|_F \leq \sqrt{n} \|A^{-1}\|_F, X \in S$$

< ロ > < 回 > < 回 > < 回 > < 回 >

2

Gradient Method Convergence results Simplified search Direction Sparse approximation

Negative gradient direction

Iterations

$$X^{(k+1)} = X^{(k)} - \alpha_k \nabla F(X^{(k)}),$$

• Steepest descent : optimal α_k that optimizes $F(X^{(k)} + \alpha D_k)$, is

$$\alpha_{k} = \frac{\left(\langle X^{(k)}A, I \rangle \langle X^{(k)}A, D_{k}A \rangle - n \langle D_{k}A, I \rangle \right)}{\left(\langle D_{k}A, I \rangle \langle X^{(k)}A, D_{k}A \rangle - \langle X^{(k)}A, I \rangle \langle D_{k}A, D_{k}A \rangle \right)}$$

• Since $||I||_F = \sqrt{n}$,

$$X^{(k+1)} = X^{(k)} - \frac{\alpha_k}{\sqrt{n} \, \|X^{(k)}A\|_F} \left(\frac{\langle X^{(k)}A, I \rangle}{\|X^{(k)}A\|_F^2} X^{(k)}A - I\right) A$$

imposing the condition $||X^{(k)}A||_F = \sqrt{n}$,

$$X^{(k+1)} = X^{(k)} - \frac{\alpha_k}{n} \left(\frac{\langle X^{(k)} A, I \rangle}{n} X^{(k)} A - I \right) A,$$

イロト イポト イヨト イヨト

Gradient Method Convergence results Simplified search Direction Sparse approximation

Algorithm 1 : CauchyCos (Steepest descent approach on $F(X) = 1 - \cos(XA, I)$)

1: Given
$$X_0 \in PSD$$

2: for $k = 0, 1, \cdots$ until a stopping criterion is satisfied, do
3: Set $w_k = \langle X^{(k)}A, I \rangle$
4: Set $\nabla F(X^{(k)}) = \frac{1}{n} \left(\frac{w_k}{n} X^{(k)}A - I \right) A$
5: Set $\alpha_k = \left| \frac{n \langle \nabla F(X^{(k)})A, I \rangle - w_k \langle X^{(k)}A, \nabla F(X^{(k)})A \rangle}{\langle \nabla F(X^{(k)})A, I \rangle \langle X^{(k)}A, \nabla F(X^{(k)})A \rangle - w_k \| \nabla F(X^{(k)})A \|_F^2} \right|$
6: Set $Z^{(k+1)} = X^{(k)} - \alpha_k \nabla F(X^{(k)})$
7: Set $X^{(k+1)} = s \sqrt{n} \frac{Z^{(k+1)}}{\|Z^{(k+1)}A\|_F}$, where $s = 1$ if $trace(Z^{(k+1)}A) > 0$, $s = -1$ else
8: end for

イロト イヨト イヨト

Gradient Method Convergence results Simplified search Direction Sparse approximation

Lemma

If $X^{(0)}A = AX^{(0)}$, then $X^{(k)}A = AX^{(k)}$, for all $k \ge 0$ in the CauchyCos Algorithm.

Lemma

If $X^{(0)}A = AX^{(0)}$, then the sequences $\{X^{(k)}\}$, $\{Z^{(k)}\}$, and $\{Z^{(k)}A\}$ generated by the CauchyCos Algorithm are uniformly bounded away from zero.

Theorem

The sequence $\{X^{(k)}\}$ generated by the CauchyCos Algorithm converges to A^{-1} .

イロト イポト イラト イラト

Gradient Method Convergence results Simplified search Direction Sparse approximation

To avoid oscillation of the steepest descent : right preconditioning

$$\widehat{D}_{k} \equiv \widehat{D}(X^{(k)}) = -\frac{1}{n} \left(\frac{\langle X^{(k)} A, I \rangle}{n} X^{(k)} A - I \right),$$
(1)

Rmk : MINRES can be seen as a steepest descent inverse-right-preconditioned by $(A^T)^{-1}$.

イロト イポト イヨト イヨト

Gradient Method Convergence results Simplified search Direction Sparse approximation

Algorithm 2 : MinCos (simplified gradient approach on $F(X) = 1 - \cos(XA, I)$)

1: Given
$$X_0 \in PSD$$

2: for $k = 0, 1, \cdots$ until a stopping criterion is satisfied, do
3: Set $w_k = \langle X^{(k)}A, I \rangle$
4: Set $\hat{D}_k = -\frac{1}{n} \left(\frac{w_k}{n} X^{(k)}A - I \right)$
5: Set $\alpha_k = \left| \frac{n \langle \hat{D}_k A, I \rangle - w_k \langle X^{(k)} A, \hat{D}_k A \rangle}{\langle \hat{D}_k A, I \rangle \langle X^{(k)} A, \hat{D}_k A \rangle - w_k \| \hat{D}_k A \|_F^2} \right|$
6: Set $Z^{(k+1)} = X^{(k)} + \alpha_k \hat{D}_k$
7: Set $X^{(k+1)} = s \sqrt{n} \frac{Z^{(k+1)}}{\|Z^{(k+1)}A\|_F}$, where $s = 1$ if $trace(Z^{(k+1)}A) > 0$, $s = -1$ else
8: end for

イロト イヨト イヨト

Gradient Method Convergence results Simplified search Direction Sparse approximation

An important issue is the building of sparse inverse preconditioners.

イロト イヨト イヨト

Gradient Method Convergence results Simplified search Direction Sparse approximation

An important issue is the building of sparse inverse preconditioners. To produce iterates that belong in S, we apply a sparsification (e.g. by thresholding the coefficients) to $Z^{(k+1)}$, before the rescaling, say

Algorithm 4 : Sparsified iterates

1: Set
$$Z^{(k+1)} = X^{(k)} + \alpha_k \widehat{D}_k$$

2: Sparsify $Z^{(k+1)}$ as $\mathcal{Z}^{(k+1)} = \mathcal{F}(Z^{(k+1)})$
3: Set $X^{(k+1)} = s\sqrt{n} \frac{\mathcal{Z}^{(k+1)}}{\|\mathcal{Z}^{(k+1)}A\|_F}$

4 A >

医下子 化

Gradient Method Convergence results Simplified search Direction Sparse approximation

An important issue is the building of sparse inverse preconditioners. To produce iterates that belong in S, we apply a sparsification (e.g. by thresholding the coefficients) to $Z^{(k+1)}$, before the rescaling, say

Algorithm 5 : Sparsified iterates

1: Set
$$Z^{(k+1)} = X^{(k)} + \alpha_k \widehat{D}_k$$

2: Sparsify $Z^{(k+1)}$ as $\mathcal{Z}^{(k+1)} = \mathcal{F}(Z^{(k+1)})$
3: Set $X^{(k+1)} = s\sqrt{n} \frac{\mathcal{Z}^{(k+1)}}{\|\mathcal{Z}^{(k+1)}A\|_F}$

The sparsification wil be realized by using a threshold tolerance, combined with a fixed bound on the maximum number of nonzero elements to be kept at each column (or row) to limit the fill-in.

マロト イラト イラト

Gradient Method Convergence results Simplified search Direction Sparse approximation

Algorithm 6 : Sparse MinCos

1: Given
$$X_0 \in PSD$$

2: for $k = 0, 1, \cdots$ until a stopping criterion is satisfied, do
3: Set $w_k = \langle X^{(k)}A, I \rangle$
4: Set $\hat{D}_k = -\frac{1}{n} \left(\frac{w_k}{n} X^{(k)}A - I \right)$
5: Set $\alpha_k = \left| \frac{n \langle \hat{D}_k A, I \rangle - w_k \langle X^{(k)}A, \hat{D}_k A \rangle}{\langle \hat{D}_k A, I \rangle \langle X^{(k)}A, \hat{D}_k A \rangle - w_k \| \hat{D}_k A \|_F^2} \right|$
6: Set $Z^{(k+1)} = X^{(k)} + \alpha_k \hat{D}_k$
7: Sparsify $Z^{(k+1)}$ as $Z^{(k+1)} = \mathcal{F}(Z^{(k+1)})$
8: Set $X^{(k+1)} = s\sqrt{n} \frac{Z^{(k+1)}}{\|Z^{(k+1)}A\|_F}$, where $s = 1$ if $trace(Z^{(k+1)}A) > 0$, $s = -1$ else
9: end for

< ロ > < 回 > < 回 > < 回 > < 回 >

Numerical Results

The examples

- from the Matlab gallery : Poisson, Lehmer, Wathen, Moler, and minij. Notice that the Poisson matrix, referred in Matlab as (Poisson, N) is the N² × N² finite differences 2D discretization matrix of the negative Laplacian on]0, 1[² with homogeneous Dirichlet boundary conditions.
- Poisson 3D (that depends on the parameter N), is the $N^3 \times N^3$ finite differences 3D discretization matrix of the negative Laplacian on the unit cube with homogeneous Dirichlet boundary conditions.

• from the Matrix Market : nos1, nos2, nos5, and nos6.

Numerical Results

The examples

- from the Matlab gallery : Poisson, Lehmer, Wathen, Moler, and minij. Notice that the Poisson matrix, referred in Matlab as (Poisson, N) is the N² × N² finite differences 2D discretization matrix of the negative Laplacian on]0, 1[² with homogeneous Dirichlet boundary conditions.
- Poisson 3D (that depends on the parameter N), is the N³ × N³ finite differences 3D discretization matrix of the negative Laplacian on the unit cube with homogeneous Dirichlet boundary conditions.
- from the Matrix Market : nos1, nos2, nos5, and nos6.

The methods

- minimizing F(X): CauchyCos (Steepest), MinCos (right Prec. Steepest)
- minimizing $\Phi(X) = \frac{1}{2} \|I XA\|_F^2$: CauchyFro (Steepest), MinRes (right. Prec Steepest)
- Stopping criteria $Min(\Phi(X^{(k)}), F(X^{(k)})) \leq \epsilon$

Matrix A	Size $(n \times n)$	$\kappa(A)$	A
Poisson (50)	n=2500	1.05e+03	sparse
Poisson (100)	n=1000	6.01e+03	sparse
Poisson (150)	n=22500	1.34e+04	sparse
Poisson (200)	<i>n</i> =40000	2.38e+04	sparse
Poisson 3D (10)	n=1000	79.13	sparse
Poisson 3D (15)	n=3375	171.66	sparse
Poisson 3D (30)	n=27000	388.81	sparse
Poisson 3D (50)	n=125000	1.05e+03	sparse
Lehmer (100)	n=100	1.03e+04	dense
Lehmer (200)	n=200	4.2e+04	dense
Lehmer (300)	<i>n</i> =300	9.5e+04	dense
minij (100)	n=100	1.63e+04	dense
minij (200)	n=200	6.51e+04	dense
moler (100)	n=100	3.84e+16	dense
moler (200)	n=200	3.55e+16	dense
nos1	n=237	2.53e+07	sparse
nos2	n=957	6.34e+09	sparse
nos5	<i>n</i> =468	2.91e+04	sparse
nos6	n=675	8.0e+07	sparse

J-P. CHEHAB

Conditioning and Preconditioning in the Cone of SPD matrices

Matrix	Size $(n \times n)$	CauchyCos	CauchyFro	MinRes	MinCos
Poisson 2D (50)	n=2500	88	132	7	6
Poisson 3D (10)	n=1000	9	12	3	2
Poisson 3D (15)	n=3375	10	14	3	2
Lehmer (10)	n=10	888	1141	21	15
Lehmer (20)	n=20	9987	49901	123	51
Minij (20)	n=20	31271	63459	209	45
Minij (30)	<i>n</i> =30	153456	629787	553	102
Moler (100)	n=100	7	83	3	3
Moler (200)	n=200	77	15243	19	12
Wathen (10)	n=341	10751	17729	68	57
Wathen (20)	n=1281	495	1112	22	16

Table : Number of iterations required for all considered methods when $\epsilon = 0.01$.

メロト メタト メヨト メヨト

2

Matrix	Size $(n \times n)$	CauchyCos	CauchyFro	MinRes	MinCos
Poisson 2D (100)	n=1000			7	7
Poisson 2D (200)	n=40000			7	7
Poisson 3D (30)	n=27000			3	3
Poisson 3D (50)	n=125000			3	3
Lehmer (50)	<i>n</i> =50			987	293
Lehmer (70)	<i>n</i> =70			1399	423
Lehmer (100)	n=100			3905	1178
Lehmer (200)	n=200			16189	4684
Minij (100)	n=100			6771	1259
Minij (200)	n=200			26961	5057
Moler (300)	<i>n</i> =300			105	22
Moler (500)	<i>n</i> =500			381	48
Moler (1000)	n=1000			1297	152
Wathen (30)	n=2821			24	17
Wathen (50)	n=7701			20	15

Table : Number of iterations required for all considered methods when $\epsilon = 0.01$.

< ロ > < 回 > < 回 > < 回 > < 回 >

æ



Figure : Convergence history for CauchyFro and CauchyCos (left), and MinRes and MinCos (right) for F(X) (up), when applied to the Wathen matrix for n = 20 and $\epsilon = 0.01$.

4 A >

3 N 4

Sparse approximation

The sparsification is based on a threshold tolerance with a limited fill-in (*Ifil*) on the matrix $Z^{(k+1)}$, at each iteration, before the scaling step to guarantee that the iterate $X^{(k+1)} \in S \cap T$.

- *thr* as the percentage of coefficients less than the maximum value of the modulus of all the coefficients in a column
- for each *i*-th column we select at most *lfil* off-diagonal coefficients among the ones that are larger in magnitude than $thr \times ||(Z^{(k+1)})_i||_{\infty}$, where $(Z^{(k+1)})_i$ represents the *i*-th column of $Z^{(k+1)}$.

Matrix	Method	$\kappa(X^{(k)}A)/\kappa(A)$	$[\lambda_{min}, \lambda_{max}]$ of $(X^{(k)}A)$	lter	% fill-in
nos1 ($Ifil = 10$)	MinCos	0.0835	[2.44e-06,2.3272]	20	3.71
$nos1(\mathit{lfil}=10)$	MinRes		[-98.66,5.40]		
nos6 (<i>Ifil</i> = 10)	MinCos	0.4218	[5.07e-06,3.1039]	20	0.45
nos6 ($Ifil = 20$)	MinCos	0.2003	[8.51e-06,3.0702]	20	0.82
nos6(lfil = 10)	MinRes		[-0.7351,2.6001]		
nos6(Ifil = 20)	MinRes		[-0.2256,2.2467]		
nos5(lfil = 5)	MinCos	0.068	[0.002,1.36]	10	1.18
nos5(Ifil = 10)	MinCos	0.0755	[00.0024,1.3103]	10	2.47
nos5(lfil = 5)	MinRes		[-20.31,2.16]		
nos5(Ifil = 10)	MinRes	0.1669	[0.0021,1.7868]	10	2.36
nos2(lfil = 5)	MinCos	0.1289	[5.2e-09,2.73]	10	0.52
nos2(Ifil = 10)	MinCos	0.0891	[7.95e-09,2.2873]	10	0.80
nos2(Ifil = 20)	MinCos	0.0700	[9.7e-09,1.9718]	10	1.14
nos2(Ifil = 5)	MinRes		[-0.3326, 2.4869]		
nos2(Ifil = 10)	MinRes	0.0970	[4.21e-09,1.5414]	10	0.93
nos2(<i>Ifil</i> = 20)	MinRes	0.0861	[4.21e-09,1.1638]	10	1.14

Performance of MinRes and MinCos when applied to the Matrix Market matrices nos1, nos2, nos5, and nos6, for $\epsilon = 0.01$, thr = 0.01, and different values of *Ifil*.

Matrix A	Size $(n \times n)$	$\kappa(X^{(k)}A)/\kappa(A)$	$[\lambda_{min}, \lambda_{max}]$ of $(X^{(k)}A)$	iter	% fil-in
wathen (30)	n=2821	0.0447	[0.0109, 1.3889]	20	0.73
wathen (50)	n=7701	0.0461	[0.0366, 1.4012]	20	0.27
wathen (70)	n=14981	0.0457	[0.0086, 1.3894]	20	0.14
wathen (100)	n=30401	0.0467	[0.0289, 1.4121]	20	6.8436e-02

Performance of MinCos applied to the Wathen matrix for different values of n and a maximum of 20 iterations, when $\epsilon = 0.01$, thr = 0.04, and Ifil = 20.

イロト イポト イヨト イヨト



Figure : Convergence history of the CG method applied to a linear system with the Wathen matrix, for n = 50, 20 iterations, $\epsilon = 0.01$, thr = 0.01, and lfil = 20, using the preconditioned generated by the MinCos Algorithm and without preconditioning.

J-P. CHEHAB Conditioning and Preconditioning in the Cone of SPD matrices



Figure : Eigenvalues distribution of A (down) and of $X^{(k)}A$ (up) after 20 iterations of the MinCos Algorithm when applied to the Wathen matrix for n = 50, $\epsilon = 0.01$, thr = 0.01, and Ifil = 20.

- The angle between a Matrix A and the identity in $C \cap S$ is a way to study the condition number of A
- The approximations to the inverse are built in a nonlinear set and take advantage of induced properties
- The gradient method is nothing else but a Forward Euler's scheme applied to a gradient flow

< 6 b

きょうきょう

- The angle between a Matrix A and the identity in $C \cap S$ is a way to study the condition number of A
- The approximations to the inverse are built in a nonlinear set and take advantage of induced properties
- The gradient method is nothing else but a Forward Euler's scheme applied to a gradient flow
 - Gradient flows and Backward Euler's method to compute minimizers of a functional using Lojasewicz inequality (M. Pierre & B. Merlet for linear spaces (2010), B. Merlet & T.N. Nguyen for manifolds, 2013)
 - Literature : gradient methods on manifolds (Projected Gardient methods along geodesiscs, A. Lichnewsky (1979)), Optimization Algorithms on Matrix Manifolds (Mahony *et al*, AMS 2007)

4 A 1

4 3 5 4 3 5 5